

Section 16.4

Parametrized Surfaces and Surface Integrals

Parametrizing Surfaces

Examples, Preview

Examples of Parametrizations of Common Surfaces

Parametrization of Graphs of Functions

Parametrization of a Plane

Parametrization of a Cylinder

Parametrization of a Sphere

Parametrization of a Cone and Helicoid

Parametrization of a Hyperboloid

Surface Area

Scalar Surface Integrals

1 Parametrizing Surfaces

by Joseph Phillip Brennan
Jila Niknejad

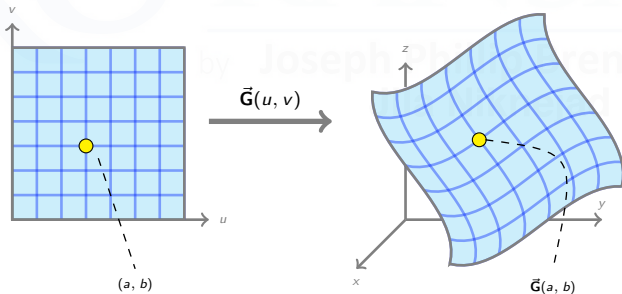
Parametrized Surfaces

A **curve** in \mathbb{R}^2 or \mathbb{R}^3 is a **one-dimensional object** and can be parametrized by a vector-valued function of **one variable**:

$$\vec{r}(t) = \langle x(t), y(t) \rangle \quad \text{or} \quad \langle x(t), y(t), z(t) \rangle.$$

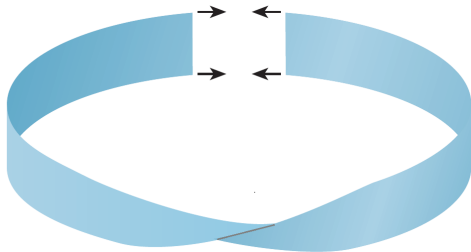
By contrast, a **surface** in \mathbb{R}^3 is a **two-dimensional object** and can be parametrized by a vector-valued function of **two variables**:

$$\vec{G}(u, v) = \langle x(u, v), y(u, v), z(u, v) \rangle.$$



Parametrized Surfaces: Quick Preview Of Examples

- $\vec{G}(u, v) = \langle 2 - 2u + v, 3 + 4v, -7 + 8u - 5v \rangle$: plane
- $\vec{G}(u, v) = \langle u, v, f(u, v) \rangle$: graph of scalar function f
- $\vec{G}(\theta, \phi) = \langle R \cos(\theta) \sin(\phi), R \sin(\theta) \sin(\phi), R \cos(\phi) \rangle$: sphere
- $\vec{G}(\theta, \phi) = \langle A \cos(\theta) \sin(\phi), B \sin(\theta) \sin(\phi), C \cos(\phi) \rangle$: ellipsoid
- $\vec{G}(r, \theta) = \langle 2 \cos(\theta) + r \cos(\theta/2), 2 \sin(\theta) + r \cos(\theta/2), r \sin(\theta/2) \rangle$: Möbius strip!



Parametrizations and Transformations

- In §15.6, we studied **transformations** (in the context of changing variables in multiple integrals).

A transformation is a function $G : E \rightarrow D$ (where E, D are regions in \mathbb{R}^2 or \mathbb{R}^3) such that

- G is one-to-one on the interior of E ;
 - G has continuous first-order partial derivatives.
- A **parametrization** of a surface S in \mathbb{R}^3 is defined in almost the same way.

It is a function $G : D \rightarrow S$ such that

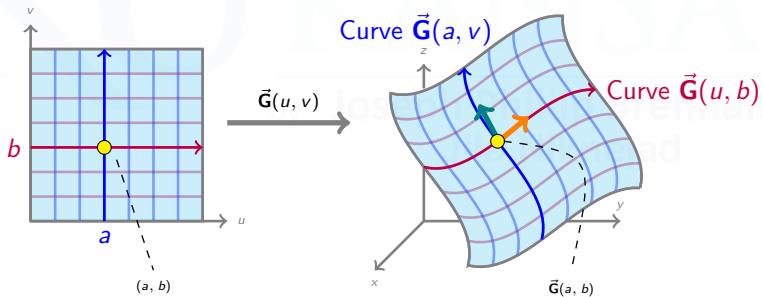
- G is onto (so that every point in S is covered);
- G is one-to-one on the interior of D ;
- G has continuous first-order partial derivatives.

Grid Curves

The **grid curves** of a surface parametrized by $\vec{G}(u, v)$ are the images of the vertical and horizontal lines in the domain, the uv -plane.

vertical line $u = a \xrightarrow{\vec{G}}$ grid curve $\vec{G}(a, v)$

horizontal line $v = b \xrightarrow{\vec{G}}$ grid curve $\vec{G}(u, b)$



2 Examples of Parametrizations of Common Surfaces

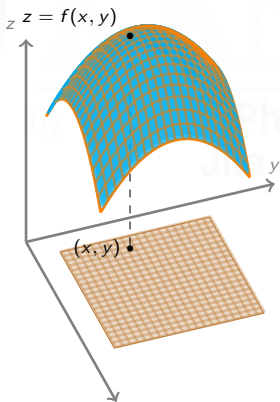
by Joseph Phillip Brennan
Jila Niknejad

Examples of Common Surfaces, Graphs of Functions

Example 1: If $f(x, y)$ is any function of two variables, its graph is a surface that can be parametrized by

$$\vec{G}(x, y) = \langle x, y, f(x, y) \rangle.$$

In this case, the grid curves are just the “lifts” of horizontal and vertical lines in \mathbb{R}^2 up to the graph.



Examples of Common Surfaces, a Plane

Example 2: The **plane** containing the point P and the vectors \vec{a} and \vec{b} can be parametrized by

$$\vec{G}(u, v) = \vec{OP} + u\vec{a} + v\vec{b}.$$

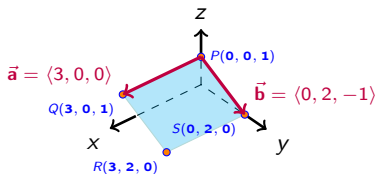
Idea: Every point in the plane can be obtained by starting at P and moving parallel to the vectors \vec{a} and \vec{b} .

E.g., a **parametrization** of parallelogram with vertices $P(0, 0, 1)$, $Q(3, 0, 1)$, $R(3, 2, 0)$ and $S(0, 2, 0)$ is

$$\vec{G}(u, v) = \underbrace{\langle 0, 0, 1 \rangle}_P + u \underbrace{\langle 3, 0, 0 \rangle}_{\vec{PQ}} + v \underbrace{\langle 0, 2, -1 \rangle}_{\vec{PS}},$$

where $0 \leq u, v \leq 1$

An **equation** of the plane is $3(y - 0) + 6(z - 1) = 0$.

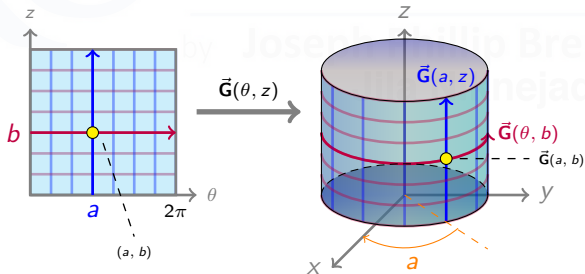


Examples of Common Surfaces, a Cylinder

Example 3: Find a parametrization for the **cylinder** $x^2 + y^2 = c^2$.

Solution: In cylindrical coordinates, the equation is $r = c$. Thus the transformation from cylindrical to rectangular is a parametrization, with parameters θ and z :

$$\vec{G}(\theta, z) = \underbrace{\langle c \cos(\theta), c \sin(\theta), z \rangle}_{\text{Cylindrical Transform. with } r=c}, \quad \theta \in [0, 2\pi], \quad z \in (-\infty, \infty)$$

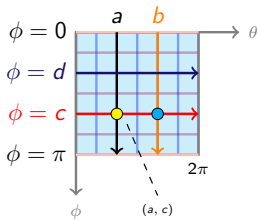


Examples of Common Surfaces, a Sphere

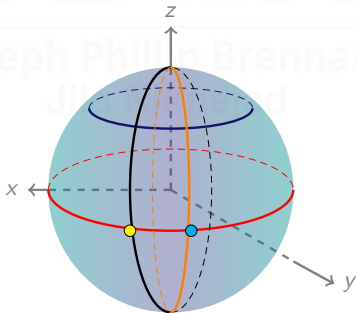
Example 4: Find a parametrization for the **sphere** $x^2 + y^2 + z^2 = c^2$.

Solution: In spherical coordinates, the equation is $\rho = c$. Thus the transformation from spherical to rectangular is a parametrization, with parameters θ and ϕ :

$$\vec{G}(\theta, \phi) = \underbrace{\langle c \cos(\theta) \sin(\phi), c \sin(\theta) \sin(\phi), c \cos(\phi) \rangle}_{\text{Spherical Transform. with } \rho=c}, \quad \theta \in [0, 2\pi], \phi \in [0, \pi]$$



$\vec{G}(\theta, \phi) \rightarrow$



Examples of Common Surfaces, a Cone

Example 5: Identify the surface parameterized by

$$\vec{G}(u, v) = \langle u \cos(v), u \sin(v), u \rangle.$$

Solution: Eliminate u and v to obtain an equation in (x, y, z) :

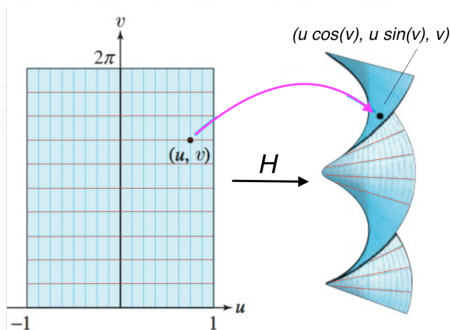
$$\begin{aligned}x^2 + y^2 &= (u \cos(v))^2 + (u \sin(v))^2 \\ &= u^2 = z^2.\end{aligned}$$

The parametric surface is a **cone**.

Example 6: The surface parameterized by

$$H(u, v) = \langle u \cos(v), u \sin(v), v \rangle$$

is called a **helicoid**.



Examples of Common Surfaces, a Hyperboloid

Example 7: Find a parametrization for the hyperboloid of one sheet

$$x^2 + y^2 - z^2 = 1$$

Solution: Don't forget that there are an infinite number of parametrizations for any surface!

We will find two methods for parametrizing this surface:

Method I: Set $z = u$. Then $x^2 + y^2 = 1 + u^2$. We can then let

$$x = \sqrt{1 + u^2} \cos(v) \quad y = \sqrt{1 + u^2} \sin(v)$$

$$\vec{\mathbf{G}}(u, v) = \langle \sqrt{1 + u^2} \cos(v), \sqrt{1 + u^2} \sin(v), u \rangle$$

Method II: Set $z = \tan(u)$. Then $x^2 + y^2 = \sec^2(u)$. We can then let

$$x = \sec(u) \cos(v) \quad y = \sec(u) \sin(v)$$

$$\vec{\mathbf{G}}(u, v) = \langle \sec(u) \cos(v), \sec(u) \sin(v), \tan(u) \rangle$$

3 Surface Area

by Joseph Phillip Brennan
Jila Niknejad

Surface Area of a Parametrized Surface

In §14.3 we calculated the **arclength** of a parametrized curve and then we used the resulting formula to define line integrals.

In a similar fashion, we will calculate the **surface area** of a parametrized surface and will eventually use it to define **surface integrals**.

Setup: Suppose we have a parametrization $G : \mathcal{R} \subseteq \mathbb{R}^2 \rightarrow \mathcal{S}$, where $\vec{G}(u, v) = (x(u, v), y(u, v), z(u, v))$. Define

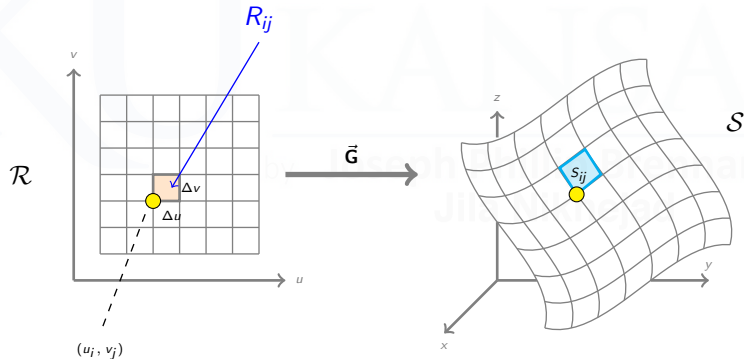
$$\vec{G}_u(u, v) = \langle x_u(u, v), y_u(u, v), z_u(u, v) \rangle,$$

$$\vec{G}_v(u, v) = \langle x_v(u, v), y_v(u, v), z_v(u, v) \rangle.$$

These vectors are tangent to the grid curves at the point $\vec{G}(u, v)$ on \mathcal{S} .

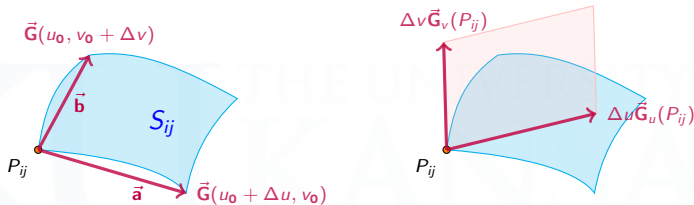
Surface Area of a Parametrized Surface

- Partition \mathcal{R} into rectangular subregions R_{ij} .
- Each subregion maps to a piece S_{ij} of the surface S .
- The boundary of S_{ij} is made up of grid curves.



Surface Area of a Parametrized Surface

Similar to the Jacobian calculations of section 15.6, we approximate S_{ij} as a rectangle of width $\vec{\mathbf{G}}_u(u_i, v_j) \Delta u$ and length $\vec{\mathbf{G}}_v(u_i, v_j) \Delta v$.



Using the parallelogram property of the cross product:

$$\begin{aligned}\text{Area}(S_{ij}) &\approx \|\vec{\mathbf{G}}_u(u_i, v_j) \Delta u \times \vec{\mathbf{G}}_v(u_i, v_j) \Delta v\| \\ &= \|\vec{\mathbf{G}}_u(u_i, v_j) \times \vec{\mathbf{G}}_v(u_i, v_j)\| \Delta u \Delta v\end{aligned}$$

Summing the areas into a Riemann sum and taking a limit yields

$$\text{Area}(S) = \iint_{\mathcal{D}} \|\vec{\mathbf{G}}_u(u, v) \times \vec{\mathbf{G}}_v(u, v)\| dA$$

Surface Area Formula — Parametrization Version

$$\text{Area}(S) = \iint_{\mathcal{D}} \|\vec{\mathbf{G}}_u(u, v) \times \vec{\mathbf{G}}_v(u, v)\| \, dA$$

Example 8: Find the surface area of the cylinder $x^2 + y^2 = 4$ between $z = 0$ and $z = 5$.

Solution: First, parametrize the cylinder and calculate partial derivatives:

$$\vec{\mathbf{G}}(u, v) = \langle 2 \cos(u), 2 \sin(u), v \rangle \quad 0 \leq u \leq 2\pi, \quad 0 \leq v \leq 5$$

$$\vec{\mathbf{G}}_u(u, v) = \langle -2 \sin(u), 2 \cos(u), 0 \rangle$$

$$\vec{\mathbf{G}}_v(u, v) = \langle 0, 0, 1 \rangle$$

Then apply the area formula:

$$\begin{aligned} \text{Area}(S) &= \int_0^{2\pi} \int_0^5 \|\langle 2 \cos(u), 2 \sin(u), 0 \rangle\| \, dv \, du \\ &= \int_0^{2\pi} \int_0^5 \underbrace{2}_{\text{Radius!}} \, dv \, du = 20\pi \end{aligned}$$

Example 9: Calculate the surface area of the sphere of radius r .

Solution: Recall that the sphere is parametrized by

$$\vec{\mathbf{G}}(\theta, \phi) = \langle r \cos(\theta) \sin(\phi), r \sin(\theta) \sin(\phi), r \cos(\phi) \rangle$$

for $\theta \in [0, 2\pi]$, $\phi \in [0, \pi]$. Therefore

$$\vec{\mathbf{G}}_{\theta} = \langle -r \sin(\theta) \sin(\phi), r \cos(\theta) \sin(\phi), 0 \rangle$$

$$\vec{\mathbf{G}}_{\phi} = \langle r \cos(\theta) \cos(\phi), r \sin(\theta) \cos(\phi), -r \sin(\phi) \rangle$$

$$\vec{\mathbf{G}}_{\theta} \times \vec{\mathbf{G}}_{\phi} = -r^2 \sin(\phi) \langle \cos(\theta) \sin(\phi), \sin(\theta) \sin(\phi), \cos(\phi) \rangle$$

$$\|\vec{\mathbf{G}}_{\theta} \times \vec{\mathbf{G}}_{\phi}\| = r^2 \sin(\phi)$$

(That should look familiar!) So the surface area of the sphere is

$$\int_0^{\pi} \int_0^{2\pi} \underbrace{r^2 \sin(\phi)}_{\text{Plug in } \rho = r \text{ in Jacobian!}} d\theta d\phi = 2\pi r^2 \int_0^{\pi} \sin(\phi) d\phi = 4\pi r^2.$$

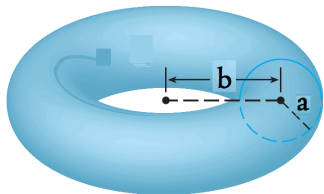
Torus (Optional)

Example 10: A torus (surface of a donut) can be obtained by rotating the circle on the yz -plane centered at $(0, b, 0)$ with radius a ($b > a > 0$) about the z -axis. The torus has a parametrization $\vec{\mathbf{G}}(\theta, \alpha)$ given by

$$\begin{aligned}x(\theta, \alpha) &= b \cos(\theta) + a \cos(\alpha) \cos(\theta) \\y(\theta, \alpha) &= b \sin(\theta) + a \cos(\alpha) \sin(\theta) \\z(\theta, \alpha) &= a \sin(\alpha)\end{aligned}$$

where $0 \leq \theta \leq 2\pi$ and $0 \leq \alpha \leq 2\pi$.

Find the surface area of the torus.



Solution: First, calculate $\|\vec{\mathbf{G}}_\theta \times \vec{\mathbf{G}}_\alpha\| = a(b + a \cos(\alpha))$.

Then, use the surface area formula:

$$\begin{aligned}\int_0^{2\pi} \int_0^{2\pi} a(b + a \cos(\alpha)) d\theta d\alpha &= 2\pi a \int_0^{2\pi} (b + a \cos(\alpha)) d\alpha \\ &= 4\pi^2 ab.\end{aligned}$$

Surface Area of a Graph

Recall that the **graph** of $z = f(x, y)$ has a natural parametrization

$$\vec{\mathbf{G}}(x, y) = \langle x, y, f(x, y) \rangle.$$

The partial derivative vectors are

$$\vec{\mathbf{G}}_x(x, y) = \langle 1, 0, f_x(x, y) \rangle$$

$$\vec{\mathbf{G}}_y(x, y) = \langle 0, 1, f_y(x, y) \rangle$$

and

$$\vec{\mathbf{G}}_x \times \vec{\mathbf{G}}_y = \langle -f_x, -f_y, 1 \rangle \quad \therefore \quad \|\vec{\mathbf{G}}_x \times \vec{\mathbf{G}}_y\| = \sqrt{1 + f_x^2 + f_y^2}.$$

Surface Area Formula — Graph Version

The part of the graph of $z = f(x, y)$ over a region \mathcal{D} in \mathbb{R}^2 has surface area

$$\iint_{\mathcal{D}} \sqrt{1 + f_x(x, y)^2 + f_y(x, y)^2} \, dA = \iint_{\mathcal{D}} \sqrt{1 + z_x^2 + z_y^2} \, dA.$$

Example 11: Calculate the surface area of the part of the saddle surface $z = xy$ lying over the unit disk \mathcal{D} .

Solution: The surface area formula (Graph Version) gives

$$\text{area} = \iint_{\mathcal{D}} \underbrace{\sqrt{1 + y^2 + x^2}}_{\sqrt{z_x^2 + z_y^2 + 1}} dA.$$

In polar coordinates, the integral becomes

$$\int_0^{2\pi} \int_0^1 \underbrace{\sqrt{1 + r^2}}_r dr d\theta = 2\pi \int_0^1 r\sqrt{1 + r^2} dr.$$

Substitute $u = 1 + r^2$, $du = 2r dr$ to get

$$\frac{2\pi}{2} \int_1^2 \sqrt{u} du = \pi \frac{2}{3} u^{3/2} \Big|_1^2 = \frac{2\pi}{3} (2\sqrt{2} - 1) \approx 3.829.$$

4 Scalar Surface Integrals

by Joseph Phillip Brennan
Jila Niknejad

Scalar Surface Integrals

Suppose that $f(x, y, z)$ is a function on a surface S parametrized by $\vec{\mathbf{G}}(u, v)$ over the domain \mathcal{R} .

The **surface integral** of f over S is defined as

$$\iint_S f(x, y, z) dS = \iint_{\mathcal{R}} f(\vec{\mathbf{G}}(u, v)) \|\vec{\mathbf{G}}_u \times \vec{\mathbf{G}}_v\| dA$$

- If $f(x, y, z) = 1$ then the surface integral is just surface area.
- If $f(x, y, z)$ represents the density of stuff per unit area, then the surface integral is the total amount of stuff.
- The symbol dS is called the **surface element** or the **area element**:

$$dS = \|\vec{\mathbf{G}}_u \times \vec{\mathbf{G}}_v\| dA_{uv}.$$

Scalar Surface Integrals: Examples

Example 12: Evaluate $\iint_S x^2 dS$, where S is $x^2 + y^2 + z^2 = 9$.

Solution: First, parametrize the sphere using spherical coordinates.

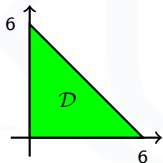
$$\vec{G}(\theta, \phi) = \underbrace{\langle 3 \sin(\phi) \cos(\theta), 3 \sin(\phi) \sin(\theta), 3 \cos(\phi) \rangle}_{\text{Spherical Transform. with } \rho=3} \quad \|\vec{G}_\theta \times \vec{G}_\phi\| = \underbrace{9 \sin(\phi)}_{\rho^2 \sin(\phi)}$$

$$\begin{aligned} \iint_S x^2 dS &= \int_0^{2\pi} \int_0^\pi 81 (\sin(\phi) \cos(\theta))^2 \sin(\phi) d\phi d\theta \\ &= 81 \left(\int_0^{2\pi} \underbrace{\cos^2(\theta)}_{\frac{1+\cos(2\theta)}{2}} d\theta \right) \left(\int_0^\pi \underbrace{\sin^3(\phi)}_{\sin(\phi)(1-\cos^2(\phi))} d\phi \right) \\ &= 81 \left(\frac{\cos^3(\phi) - 3 \cos(\phi)}{3} \Big|_0^\pi \right) \left(\frac{2\theta + \sin(2\theta)}{4} \Big|_0^{2\pi} \right) = 108\pi. \end{aligned}$$

Scalar Surface Integrals: Examples

Example 13: Evaluate $\iint_S yz \, dS$, where S is the part of the plane $x + y + z = 6$ that lies in the first octant.

Solution: Parametrize S as $\vec{\mathbf{G}}(x, y) = (x, y, 6 - x - y)$, where $(x, y) \in \mathcal{D}$.



$$\begin{aligned}\vec{\mathbf{G}}_x &= \langle 1, 0, -1 \rangle & \vec{\mathbf{G}}_x \times \vec{\mathbf{G}}_y &= \langle 1, 1, 1 \rangle \\ \vec{\mathbf{G}}_y &= \langle 0, 1, -1 \rangle & \|\vec{\mathbf{G}}_x \times \vec{\mathbf{G}}_y\| &= \sqrt{3}\end{aligned}$$

$$\begin{aligned}\iint_S yz \, dS &= \iint_{\mathcal{D}} y(6 - x - y)\sqrt{3} \, dA = \sqrt{3} \int_0^6 \int_0^{6-y} (6y - xy - y^2) \, dx \, dy \\ &= \sqrt{3} \int_0^6 \left(\frac{y^3}{2} - 6y^2 + 18y \right) dy = 54\sqrt{3}\end{aligned}$$